

# INTERNATIONAL STANDARD

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**Maritime navigation and radiocommunication equipment and systems – Global navigation satellite systems (GNSS) –  
Part 7: Satellite based augmentation system (SBAS) L1 – Receiver equipment –  
Performance standards, methods of testing and required test results**



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INTERNATIONAL  
ELECTROTECHNICAL  
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## CONTENTS

FOREWORD.....	5
INTRODUCTION.....	7
1 Scope.....	9
2 Normative references .....	9
3 Terms, definitions and abbreviated terms .....	10
3.1 Terms and definitions.....	10
3.2 Abbreviated terms.....	11
4 Minimum GNSS and SBAS performance standard .....	13
4.1 General.....	13
4.2 SBAS L1 receiver equipment .....	13
4.2.1 Minimum facilities .....	13
4.2.2 Configuration.....	14
4.2.3 Quality assurance.....	14
4.3 Performance standards for SBAS L1 receiver equipment .....	14
4.3.1 General .....	14
4.3.2 Equipment output .....	14
4.3.3 Accuracy .....	16
4.3.4 Acquisition.....	17
4.3.5 Availability.....	17
4.3.6 Dynamic range .....	17
4.3.7 Effects of specific interfering signals.....	17
4.3.8 Position update.....	18
4.3.9 SBAS input and processing .....	18
4.3.10 Navigational status indications.....	19
4.3.11 Operation under typical interference conditions .....	23
4.3.12 Output of COG, SOG and UTC .....	23
5 SBAS technical characteristics .....	24
5.1 General.....	24
5.2 SBAS L1 SIS RF characteristics .....	25
5.3 SBAS L1 SIS message characteristics .....	25
5.3.1 Identification.....	25
5.3.2 L1 C/A PRN Code for SBAS .....	26
5.3.3 SBAS data format.....	27
6 Methods of testing and required test results .....	28
6.1 Test sites .....	28
6.2 Test sequence .....	29
6.3 Test signals .....	29
6.4 Determination of accuracy .....	30
6.5 Environmental conditions .....	31
6.6 General requirements .....	31
6.7 Alert requirements .....	31
6.8 Presentation requirements .....	31
6.9 Performance check.....	31
6.10 SBAS L1 receiver tests descriptions .....	32
6.10.1 SBAS L1 receiver equipment .....	32
6.10.2 Configuration.....	32

6.10.3	Position output.....	32
6.10.4	Equipment output .....	32
6.10.5	Static accuracy and availability.....	32
6.10.6	Static accuracy with angular movement of the antenna.....	33
6.10.7	Dynamic accuracy .....	33
6.10.8	Acquisition.....	33
6.10.9	Sensitivity and dynamic range .....	34
6.10.10	Effects on specific interfering signals.....	34
6.10.11	Position update.....	34
6.10.12	SBAS input and processing .....	35
6.10.13	SBAS message processing.....	35
6.10.14	SBAS GEO satellite selection and switching .....	38
6.10.15	Navigational status indications.....	39
6.10.16	Test for typical interference conditions.....	41
6.10.17	Accuracy of COG and SOG.....	43
6.10.18	Validity of COG and SOG information .....	44
6.10.19	Output of UTC .....	44
6.10.20	Validation material for tropospheric model.....	44
Annex A (normative) High level procedure for SBAS navigation computation .....		45
A.1	GPS L1 signal processing .....	45
A.2	SBAS L1 signal processing .....	45
A.3	Application of SBAS messages .....	45
A.4	SBAS position computation.....	47
A.4.1	General .....	47
A.4.2	Weighted least squares algorithm .....	47
A.4.3	SBAS-based standard residual error.....	48
Annex B (normative) Sentences to support SBAS L1 receiver operation .....		49
B.1	General.....	49
B.2	80GBS – GNSS satellite fault detection .....	49
B.3	GFA – GNSS Fix Accuracy and Integrity .....	51
B.4	GNS – GNSS fix data.....	52
B.5	GRS – GNSS Range residuals .....	58
B.6	GSA – GNSS DOP and active satellites .....	61
B.7	GSN – GNSS SBAS navigation message .....	65
B.8	GSV – GNSS Satellites in View.....	66
B.9	RMC – Recommended minimum specific GNSS data .....	69
B.10	VTG – Course over ground and ground speed .....	71
Annex C (informative) GNSS interference, jamming and spoofing .....		72
C.1	General.....	72
C.2	Interference .....	72
C.3	Jamming .....	72
C.4	Spoofing .....	73
Annex D (normative) Alert management.....		74
Bibliography.....		75
Table 1 – Output sentences defined for positioning purposes.....		15
Table 2 – Output sentences for integration in other navigational aids.....		16

Table 3 – Required horizontal position accuracy and integrity for general navigation ..... 19

Table 4 – Accuracy of COG ..... 24

Table 5 – SBAS L1 SIS RF characteristics ..... 25

Table 6 – SBAS Ranging C/A Codes ..... 26

Table 7 – SBAS message format ..... 27

Table 8 – SBAS Message Types ..... 28

Table 9 – Broad-band interference ..... 42

Table 10 – Pulsed interference ..... 42

Table 11 – Continuous wave interference ..... 42

Table 12 – Broad-band interference ..... 43

Table D.1 – Required alerts and their classification ..... 74

## INTERNATIONAL ELECTROTECHNICAL COMMISSION

**MARITIME NAVIGATION AND RADIOCOMMUNICATION EQUIPMENT AND SYSTEMS – GLOBAL NAVIGATION SATELLITE SYSTEMS (GNSS) –****Part 7: Satellite based augmentation system (SBAS) L1 – Receiver equipment – Performance standards, methods of testing and required test results**

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The text of this International Standard is based on the following documents:

Draft	Report on voting
80/1104/FDIS	80/1114A/RVD

Full information on the voting for its approval can be found in the report on voting indicated in the above table.

The language used for the development of this International Standard is English.

This document was drafted in accordance with ISO/IEC Directives, Part 2, and developed in accordance with ISO/IEC Directives, Part 1 and ISO/IEC Directives, IEC Supplement, available at [www.iec.ch/members\\_experts/refdocs](http://www.iec.ch/members_experts/refdocs). The main document types developed by IEC are described in greater detail at [www.iec.ch/publications](http://www.iec.ch/publications).

A list of all parts in the IEC 61108 series, published under the general title *Maritime navigation and radiocommunication equipment and systems – Global navigation satellite systems (GNSS)*, can be found on the IEC website.

The committee has decided that the contents of this document will remain unchanged until the stability date indicated on the IEC website under [webstore.iec.ch](http://webstore.iec.ch) in the data related to the specific document. At this date, the document will be

- reconfirmed,
- withdrawn, or
- revised.

## INTRODUCTION

Satellite based augmentation system (SBAS) is designed to augment Global Navigation Satellite System (GNSS) by broadcasting additional signals from geostationary (GEO) satellites. The basic scheme is to use a set of ground monitoring stations (at precisely surveyed locations) to receive GNSS signals that are processed and transmitted to the master station(s) which formulates the correction messages applicable to users within the service area (i.e. ionospheric errors, satellite position/clock errors, etc.). These corrections are then transmitted to navigation payloads via uplink stations on GEO satellites. The GEO satellites then transmit these corrections in a GNSS-like signal across the service area. An integrity message is also broadcasted enabling receivers to remove errors in the GNSS signal for increased position accuracy and integrity. Users are notified within a few seconds of information that could lead to position error.

SBAS are civil aviation safety-critical system and are designed according to an international standard (SARPs:2023). So far, SBAS have already been commissioned by the US (Wide Area Augmentation System – WAAS), Europe (European Geostationary Navigation Overlay Service – EGNOS), Japan (Michibiki Satellite Augmentation System – MSAS) and India (GPS Aided GEO Augmented Navigation – GAGAN). At September 2022, analogous systems are under commissioning or development in other regions of the world such as BeiDou Satellite Based Augmentation System – BDSBAS in China, System of Differential Correction and Monitoring – SDCM in Russia, Korea Augmentation Satellite System – KASS in Republic of Korea, Southern Positioning Augmentation System – SouthPAN in Australia and New Zealand, Augmented Navigation for Africa – ANGA and the Solución de Aumentación para Caribe, Centro y Sudamérica – SACCSA in South/Central America and the Caribbean.

The maritime community is interested in using SBAS for ocean waters, coastal waters and harbour entrances/approaches in order to fulfil the agreed international operational performance requirements (IMO Resolution A.1046(27)), especially where there is no other augmentation service available (i.e. DGPS/DGLONASS) or in poorly covered environments. Besides, when Ground Based Augmentation Systems (GBAS) are available, SBAS could become either the primary augmentation system or could act as a back-up. SBAS aims at providing satellite clock/ephemeris corrections, ionospheric corrections and integrity information to GNSS signals that meet maritime requirements, enhanced accuracy and integrity information.

IMO MSC.401(95) and IEC 61108-4 (Shipborne DGPS and DGLONASS maritime radio beacon receiver equipment) allow the use of different augmentation signals in shipborne receivers but there is neither an IMO or IEC standard on how to process and implement SBAS signals in shipborne receivers. One of the operational and functional requirements (Module B) of IMO Resolution MSC.401(95) is that the equipment has the facilities to process augmentation data in accordance with the appropriate methods, e.g. Recommendation ITU-R M.823, RTCM 10410, or other relevant standards, already existing or still to be developed in particular for satellite based augmentation system (SBAS) adoption. This document provides the requested standard for SBAS L1 augmenting GPS L1.

Most of recent maritime GNSS receiver models are SBAS compatible but present important differences in their performance since they are not certified according to any specific test standard.

IEC 61108 is a series of IEC standards for "Maritime navigation and radio-communication equipment and systems – Global navigation satellite systems (GNSS)". IEC has published International Standards for the following GNSS systems: IEC 61108-1 for GPS, IEC 61108-2 for GLONASS, IEC 61108-3 for Galileo, IEC 61108-5 for BDS and IEC 61108-6 for IRNSS. In addition, IEC has published International Standard IEC 61108-4 for DGPS and DGLONASS which are Differential Global Navigation Satellite System (DGNSS) enhancing the primary GNSS constellations (GPS and GLONASS).

This document includes the minimum performances for the shipborne receivers, using SBAS L1 signals augmenting GPS L1, in order to be compliant with the IMO Resolution A.1046(27) operational requirements for ocean waters, harbour entrances, harbour approaches and coastal waters, along with the methods of testing and required test results.

Satellite Based Augmentation Systems (SBAS) are available in several regions worldwide to augment GPS L1 frequency by broadcasting additional SBAS L1 signals:

- SBAS are designed according to the same international standard (SARPs:2023).
- GPS L1 signal specification is presented in the GPS Interference Specification (IS-GPS-200).

A description of the GPS Standard Positioning Service Performance Standard (GPS-SPS-PS) is available at <https://www.gps.gov>.

NOTE A standard including dual-frequency multi-constellation (DFMC) SBAS services will be considered when appropriate.

# MARITIME NAVIGATION AND RADIOCOMMUNICATION EQUIPMENT AND SYSTEMS – GLOBAL NAVIGATION SATELLITE SYSTEMS (GNSS) –

## Part 7: Satellite based augmentation system (SBAS) L1 – Receiver equipment – Performance standards, methods of testing and required test results

### 1 Scope

This part of IEC 61108 specifies the minimum performance standards, methods of testing and required test results for Satellite based augmentation system (SBAS) shipborne receiver equipment, which uses L1 signals from GPS and satellite based augmentation system (SBAS) in order to improve the estimated GPS position.

This document addresses the use of SBAS L1 to provide augmentation to the GPS shipborne receiver (IMO Resolution MSC.112(73)). This document includes the minimum performances for SBAS L1 maritime receivers to be obtained by the receiver equipment under coverage of SBAS service in order to be compliant with the IMO Resolution A.1046(27) describing operational requirements for ocean waters, harbour entrances, harbour approaches and coastal waters.

### 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60721-3-6:1987, *Classification of environmental conditions – Part 3: Classification of groups of environmental parameters and their severities – Ship environment*

IEC 60945, *Maritime navigation and radiocommunication equipment and systems – General requirements – Methods of testing and required test results*

IEC 61108-1:2003, *Maritime navigation and radiocommunication equipment and systems – Global navigation satellite systems (GNSS) – Part 1: Global positioning system (GPS) – Receiver equipment – Performance standards, methods of testing and required test results*

IEC 61162-1, *Maritime navigation and radiocommunication equipment and systems – Digital interfaces – Part 1: Single talker and multiple listeners*

IEC 61162-2, *Maritime navigation and radiocommunication equipment and systems – Digital interfaces – Part 2: Single talker and multiple listeners, high-speed transmission*

IEC 61162-450, *Maritime navigation and radiocommunication equipment and systems – Digital interfaces – Part 450: Multiple talkers and multiple listeners – Ethernet interconnection*

IEC 62923-1, *Maritime navigation and radiocommunication equipment and systems – Bridge alert management – Part 1: Operational and performance requirements, methods of testing and required test results*

IEC 62923-2, *Maritime navigation and radiocommunication equipment and systems – Bridge alert management – Part 2: Alert and cluster identifiers and other additional features*